# Rahim Hossain

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## RESEARCH INTERESTS

Machine Learning | Deep Learning | Computer Vision | Natural Language Processing | Robotics

#### **EDUCATION**

**SUNY Binghamton** 

PhD in Computer Science

Binghamton, New York Aug 2024-present

**SUNY Binghamton** 

MS in Computer Science

Binghamton, New York Jan 2023–May 2024

Bangladesh University of Engineering and Technology

B.Sc. in Electrical and Electronic Engineering

Dhaka, Bangladesh

Apr 2016–Jan 2022

May 2023 - Current

#### WORK EXPERIENCE

**SUNY Binghamton** 

Binghamton, New York

Research Assistant, RT Lab

- Developing an algorithm for efficient test time adaptation
- Developed Deep Neural Network Architecture for Detecting Spotted Lanternfly Using Energy Efficient Wide Area Network

## Cobalt Speech and Language, Inc

Remote

Research Scientist

Mar 2022–Dec 2022

- Specialized in Natural Language Processing (NLP) and Understanding (NLU), contributing significantly to the company's ambitious "Call Summarization" project.
- Trained large language models including BART, BERT, and LED, gaining extensive experience with transformer models and enhancing expertise in developing advanced NLP solutions.

#### Research Experience

#### System design to detect Spotted Lantern Fly

Aug 2023-Current

Supervisor: Dr. Kyoung-Don Kang, Dr. Jayson Boubin and Dr. Dali Ismail

 In this research, we developed a end to end system to detect spotted lantern fly using DNN model and LoRa network

#### Investigated Linear Neural Network's Vulnerability

May 2023–Aug 2023

Supervisor: Dr. Adnan Siraj Rakin

 In this research, the primary objective is to investigate the effect of elimination of non linear activation in the DNN in terms of robustness.

#### Security Threat in Source Free Domain Adaptation

Jan 2023–March 2023

Supervisor: Dr. Adnan Siraj Rakin

— We investigated the effect of a source adversary which may inject a hidden malicious behavior (Backdoor/Trojan) during source training and potentially transfer it to the target domain even after benign training by the victim (target do-main owner). We also built a defense method for the attack as well.

Weight Pruning May 2021–Dec 2021

Supervisor: Dr. Manar Samad

 We investigated the effect of weight pruning in unsupervised learning setup. We also proposed a weight perturbation method.

#### **PUBLICATIONS**

- 1. Sabbir Ahmed, Abdullah Al Arafat, Mamshad Nayeem Rizve, Rahim Hossain, Zhishan Guo, Adnan Siraj Rakin, "SSDA: Secure Source-Free Domain Adaptation," International Conference on Computer Vision(ICCV), 2023. [Paper]
- 2. M. D. Samad, R. Hossain and K. M. Iftekharuddin, "Dynamic Perturbation of Weights for Improved Data Reconstruction in Unsupervised Learning," 2021 International Joint Conference on Neural Networks (IJCNN), 2021, pp. 1-7, doi: 10.1109/IJCNN52387.2021.9533539. [Paper]
- 3. R. Hossain and M. D. Samad, "A Hybrid Clustering Pipeline for Mining Baseline Local Patterns in 3D Point Cloud," 2021 6th International Conference for Convergence in Technology (I2CT), 2021, pp. 1-6, doi: 10.1109/I2CT51068.2021.9418095.[Paper]

### SIGNIFICANT PROJECTS

- Third Eye: In this project, I extended my previous smart stick project. I added LoRa to communicate with a host. The camera module detects the objects and we then send the objects to a receiver node using LoRa .[details]
- Reinforcement Learning for autonomous navigation using CARLA: In this project, we presented a RL-based navigation system for autonomous vehicles using the CARLA simulation platform. The proposed system employs a Q learning RL algorithm method, to learn the optimal actions for navigating a complex urban environment. [details]
- Source Hypothesis Transfer for Unsupervised Domain Adaptation: In this project, we investigated the benchmark results achieved in SHOT(Source hypothesis transfer for unsupervised domain adaptation) paper. Furthermore, we evaluated the effectiveness of SHOT in closed-set domain adaptation for various benchmark datasets to demonstrate its effectiveness. [details]
- Smart Stick for blind people Using Raspberry pi: It uses two ultrasonic sensors HC SR 04 to detect the depth below or the obstacles in between. Along with that it uses Arduino and Raspberry pi as the main controller. Whenever there is any obstacle in the path. The sensor detects the distance from the obstacle and send to the controller. We used a camera module which is controlled by raspberry pi. The camera detects the yellow line to tell the blind person whether he is on the track or not. [details]
- Stock increment or decrement prediction from stock data: We used a Stock data set which had multiple stock data stacked together in a list of data frames. Each stock data had columns they are (Open, High, Low, Close, Volume). We had to make the labels ourselves and classify it using a LSTM model. [details]
- Voice Controlled Vehicle: Design and implementation of a robot that follows voice commands based on speech recognition algorithms. [details]
- Line Following Bot: Design of a robot capable of line following based on Digital Logic Design [details]

### SKILLS

- Programming Languages: Python, MATLAB, C, C++, Golang, Intel-8086 Assembly
- Simulation & Design Tools: ROS, PSpice, Simulink, AutoCAD, Verilog
- Machine Learning Libraries: PyTorch, Tensorflow, Keras, Scikit-Learn

## Relevant Graduate Course-works

Machine Learning | Deep Learning | Intelligent Mobile Robotics | Design and Analysis of Algorithm | Computer Architecture | IoT | OS | HPC

#### Awards and Honors

- Ebay ML Challenge 3rd Position (2023)
- Industrial Automation Challenge (Robotic Competition) Bangladesh University of Engineering and Technology, Won 2nd position among many teams from the whole country.
- Technical Scholarship, Bangladesh University of Engineering and Technology (2016 and 2018)
- Bangladesh Education Board Scholarship in Higher Secondary Certificate (HSC) Examination (2015)